

Theory Uncertainties from Nuisance Parameters.

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SCET 2019 Workshop
San Diego, March 27, 2019

[arxiv:1904.soon]



Theory Uncertainties and Correlations.

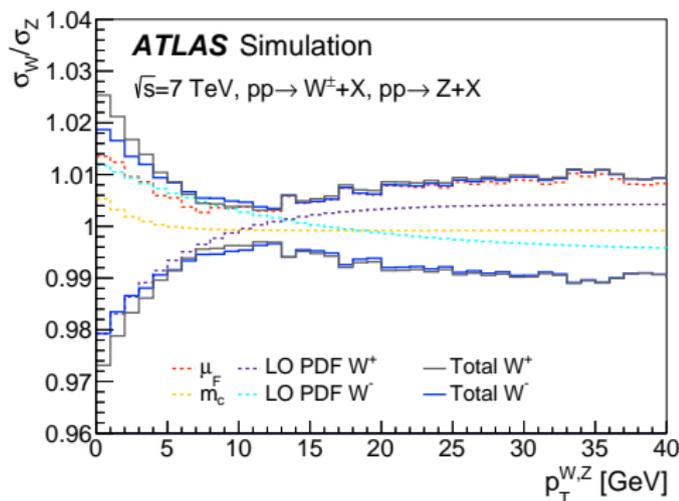
Reliable theory uncertainties are essential for any precision studies and interpretation of experimental measurements

- Especially when theory uncertainties \gtrsim experimental uncertainties
- Correlations can have significant impact
 - ▶ In fact, whenever one combines more than a single measurement, one should ask how the theory uncertainties in the predictions for each measurement are correlated with each other
 - ▶ Correlations among different points in a resummed spectrum
 - ▶ Correlations between predictions for different Q , processes, observables, ...
- So far we have (mostly) been skirting the issue
 - ▶ However, experimentalists have to treat theory uncertainties like any other systematic uncertainty, and in absence of anything better they have to make something up based on naive scale variations
 - ▶ In likelihood fits, some (possibly enveloped) scale variation impact will get treated as a free nuisance parameter and floated in the fit

Example: Measurement of the W Mass.

Small $p_T^W < 40$ GeV is the relevant region for m_W

- Needs very precise predictions for p_T^W spectrum
- $\simeq 2\%$ uncertainties in p_T^W translate into $\simeq 10$ MeV uncertainty in m_W
- Direct theory predictions for p_T^W are insufficient



⇒ **Strategy:** Exploit precisely measured Z p_T spectrum to get best possible description for W

- ▶ Regardless how precisely $d\sigma(W)/dp_T$ can be calculated directly, one always wants to exploit Z data to maximize precision

Extrapolating from Z to W .

$$\underbrace{\frac{d\sigma(W)}{dp_T}}_{\text{needed}} = \underbrace{\left[\frac{d\sigma(Z)}{dp_T} \right]_{\text{measured}}}_{\text{measure precisely}} \times \underbrace{\left[\frac{d\sigma(W)/dp_T}{d\sigma(Z)/dp_T} \right]_{\text{theory}}}_{\text{calculate precisely theory uncertainties cancel}}$$

- Ratio is just a proxy
 - ▶ More generally: Combined fit to both processes
 - ▶ Tuning Pythia on Z and using it to predict W is one example of this

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- Ratio is just a proxy
 - ▶ More generally: Combined fit to both processes
 - ▶ Tuning Pythia on Z and using it to predict W is one example of this
- **Crucial Caveat:** Cancellation fundamentally relies on theory correlations
 - ▶ Take 10% theory uncertainty on $d\sigma(W)$ and $d\sigma(Z)$
 - 99.5% correlation yields 1% uncertainty on their ratio
 - 98.0% correlation yields 2% uncertainty on their ratio – 2× larger!
- One of many examples, this happens whenever experiments extrapolate from some control region or process to the signal region

Theory Correlations.

Correlations only come from common sources of uncertainties

- Straightforward for unc. due to input parameters ($\alpha_s(m_Z)$, PDFs, ...)

What to do about perturbative theory uncertainties?

- ✗ Scale variations are not quantitatively reliable to begin with
- ✗ Moreover, they are inherently ill-suited for correlations
 - ✗ Scales are not physical parameters with an uncertainty that can be propagated, they simply specify a particular perturbative scheme
 - ✗ They are not the underlying source of uncertainty, i.e., they do not become better known at higher order
 - ✗ Taking an envelope is not a linear operation and so does not propagate
 - ✗ Trying to decide how to correlate scale variations (e.g. between processes) is really just a bandaid, but not addressing the real problem

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 - ✗ Trying to decide how to correlate scale variations (e.g. between processes) is really just a bandaid, but not addressing the real problem
- ✗ Even the most sophisticated profile scale variations are insufficient
 - ✗ The profile shapes are designed to turn off resummation and match to fixed-order, not to capture correlations in the spectrum
 - ✗ See e.g. inconsistent uncertainties from spectrum vs. cumulant scales

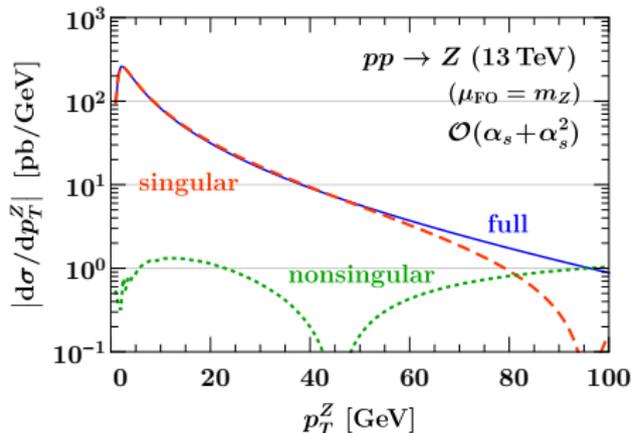
Power Expansion.

Define scaling variable $\tau \equiv p_T^2/m_V^2, \mathcal{T}_0/m_V, \dots$ and expand in powers of τ

$$\begin{aligned} \frac{d\sigma}{d\tau} &= \delta(\tau) + \alpha_s \left[\frac{\ln \tau}{\tau} + \frac{1}{\tau} + \delta(\tau) + f_1^{\text{nons}}(\tau) \right] \\ &+ \alpha_s^2 \left[\frac{\ln^3 \tau}{\tau} + \frac{\ln^2 \tau}{\tau} + \frac{\ln \tau}{\tau} + \frac{1}{\tau} + \delta(\tau) + f_2^{\text{nons}}(\tau) \right] \\ &+ \left[\begin{array}{ccccccc} \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \end{array} + \dots \right] \\ &= \qquad \qquad \qquad d\sigma^{(0)}/d\tau \qquad \qquad \qquad + \mathcal{O}(\tau)/\tau \end{aligned}$$

• For small $\tau \ll 1$

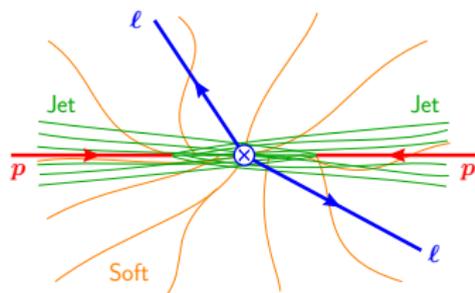
- ▶ **Logarithmic terms** completely dominate perturbative series
- ▶ Their all-order structure is actually simpler and more universal, which allows their resummation
- ▶ Also holds the key for a rigorous treatment of theory correlations



Factorization and Resummation.

Leading-power spectrum factorizes into hard, collinear, and soft contributions, e.g. for p_T

$$\begin{aligned} \frac{d\sigma^{(0)}}{d\vec{p}_T} &= \sigma_0 H(Q, \mu) \int d^2\vec{k}_a d^2\vec{k}_b d^2\vec{k}_s \\ &\times B_a(\vec{k}_a, Qe^Y, \mu, \nu) B_b(\vec{k}_b, Qe^{-Y}, \mu, \nu) \\ &\times S(\vec{k}_s, \mu, \nu) \delta(\vec{p}_T - \vec{k}_a - \vec{k}_b - \vec{k}_s) \end{aligned}$$



- Each function is a renormalized object with an associated RGE
 - ▶ Structure depends on type of variable but is universal for all hard processes
- ⇒ Dependence on p_T and Q is fully determined to all orders by a coupled system of differential equations
 - ▶ Their solution leads to resummed predictions
 - ▶ Each resummation order (only) requires as ingredients anomalous dimensions and boundary conditions entering the RG solution

Simplest Example: Multiplicative RGE.

All-order RGE and its solution

$$\mu \frac{dH(Q, \mu)}{d\mu} = \gamma_H(Q, \mu) H(Q, \mu)$$
$$\Rightarrow H(Q, \mu) = H(Q) \times \exp \left[\int_Q^\mu \frac{d\mu'}{\mu'} \gamma_H(Q, \mu') \right]$$

Necessary ingredients

- Boundary condition

$$H(Q) = 1 + \alpha_s(Q) h_1 + \alpha_s^2(Q) h_2 + \dots$$

- Anomalous dimension

$$\gamma_H(Q, \mu) = \alpha_s(\mu) [\Gamma_0 + \alpha_s(\mu) \Gamma_1 + \dots] \ln \frac{Q}{\mu}$$
$$+ \alpha_s(\mu) [\gamma_0 + \alpha_s(\mu) \gamma_1 + \dots]$$

- ⇒ Resummation is determined by coefficients of three fixed-order series
- ▶ True regardless of how RGE is solved in more complicated cases

Theory Nuisance Parameters.

Perturbative series at leading power is determined to all orders by a coupled system of differential equations (RGEs)

- Each resummation order only depends on a few semi-universal parameters
- **Unknown parameters** at higher orders are the actual sources of perturbative theory uncertainty

order	boundary conditions			anomalous dimensions			
	h_n	s_n	b_n	γ_n^h	γ_n^s	Γ_n	β_n
LL	h_0	s_0	b_0	—	—	Γ_0	β_0
NLL'	h_1	s_1	b_1	γ_0^h	γ_0^s	Γ_1	β_1
NNLL'	h_2	s_2	b_2	γ_1^h	γ_1^s	Γ_2	β_2
N ³ LL'	h_3	s_3	b_3	γ_2^h	γ_2^s	Γ_3	β_3
N ⁴ LL'	h_4	s_4	b_4	γ_3^h	γ_3^s	Γ_4	β_4

- **Basic Idea:** Treat them as **theory nuisance parameters**
 - ✓ Vary them independently to estimate the theory uncertainties
 - ✓ Impact of each independent nuisance parameter is fully correlated across all kinematic regions and processes
 - ✓ Impact of different nuisance parameters is fully uncorrelated
- **Price to Pay:** Calculation becomes quite a bit more complex

Numerous Advantages.

Immediately get all benefits of parametric uncertainties

- ✓ Encode correct correlations
- ✓ Can be propagated straightforwardly
 - ▶ Including Monte Carlo, BDTs, neural networks, ...
- ✓ Can be consistently included in a fit and constrained by data
 - ▶ Even okay to use control measurements to reduce theory uncertainties
 - ▶ Due to central-limit theorem, total theory uncertainty becomes Gaussian

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Additional theory benefits compared to scale variations

- Uncertainties can be evaluated in one space and propagated to another (Fourier conjugate, cumulant, spectrum)
- Can do partial orders and fully exploit all known higher-order information
 - ▶ Can account for new structures appearing at higher order
- Fully factorizes the uncertainties
 - ▶ Can study perturbative convergence at level of individual building blocks
 - ▶ Much safer against accidental underestimates due to multiple parameters

How to Vary What.

- **Level 1:** At given order vary parameters around their known values

$$c_0 + \alpha_s(\mu) [c_1 + \alpha_s(\mu) c_2 + \dots] \rightarrow c_0 + \alpha_s(\mu) (c_1 + \tilde{\theta}_1)$$

- ▶ Simpler but perhaps less robust

- **Level 2:** Implement the full next order in terms of unknown parameters

$$c_0 + \alpha_s(\mu) [c_1 + \alpha_s(\mu) c_2 + \dots] \rightarrow c_0 + \alpha_s(\mu) [c_1 + \alpha_s(\mu) \theta_2]$$

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- In general, can have combination of both

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Note: Some parameters are actually functions of additional variables

- E.g. beam function constants, auxiliary dependences (jet radius, ...)
- In principle, one needs to parametrize an unknown function
 - ▶ Can e.g. expand/parametrize in terms of appropriate functional basis
 - ▶ Compared to scale variations, choices are now explicit and testable

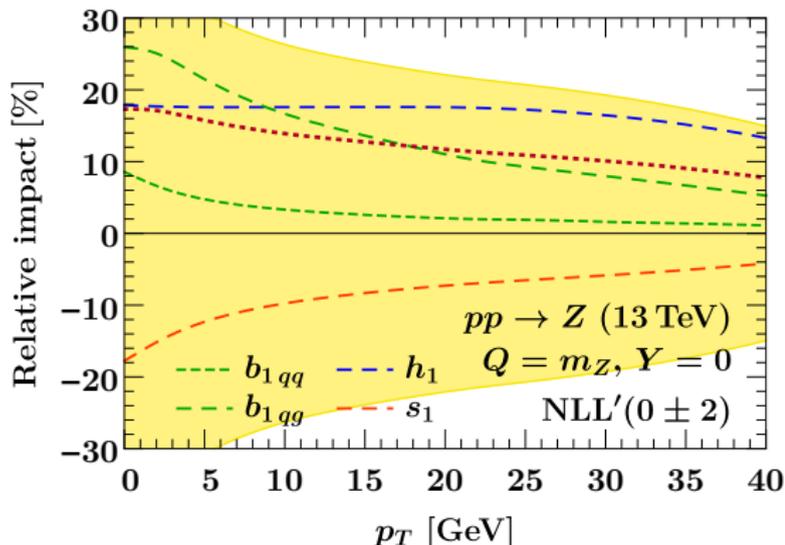
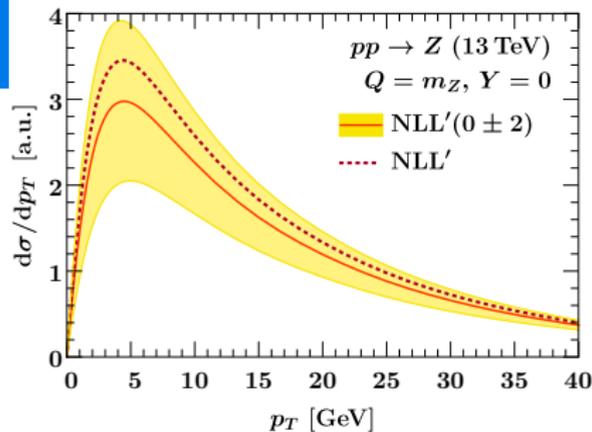
Z p_T Spectrum.

For illustration use

- Level 1: $\tilde{\theta}_i = (0 \pm 0.25) \times c_i$
- Level 2: $\theta_i = (0 \pm 2) \times c_i$
(with the true values for c_i)

Relative impact of different nuisance parameters

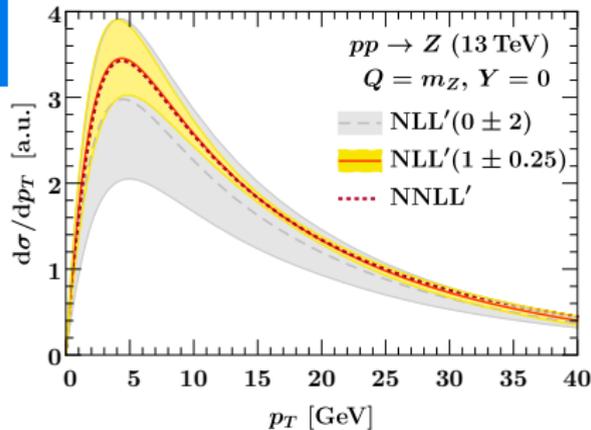
- h_1
- $b_1: q \rightarrow q, g \rightarrow q$
- s_1



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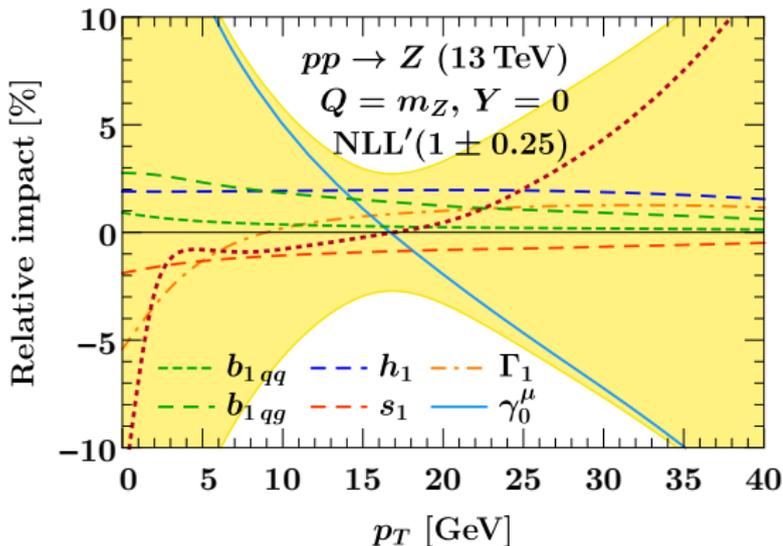
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Relative impact of different nuisance parameters

- h_1
- γ_0^μ
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- Γ_1
- s_1



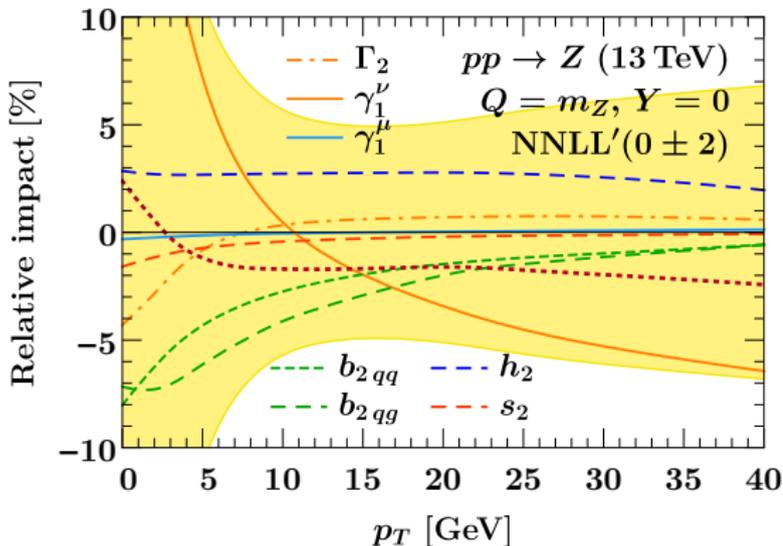
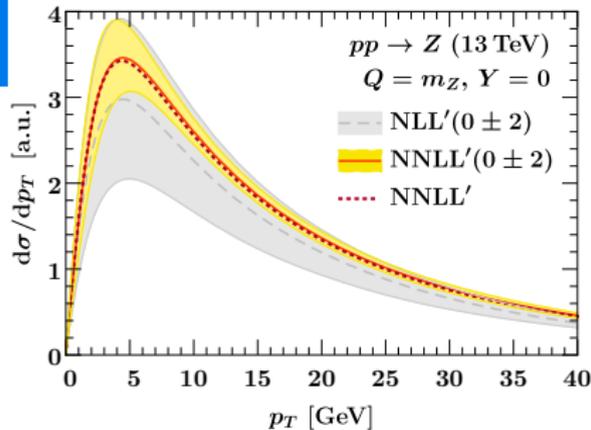
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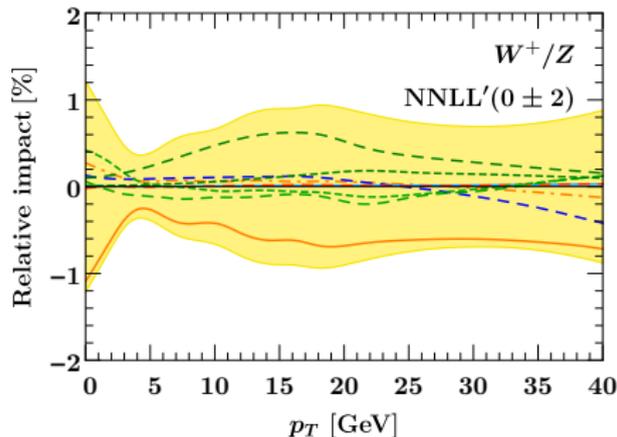
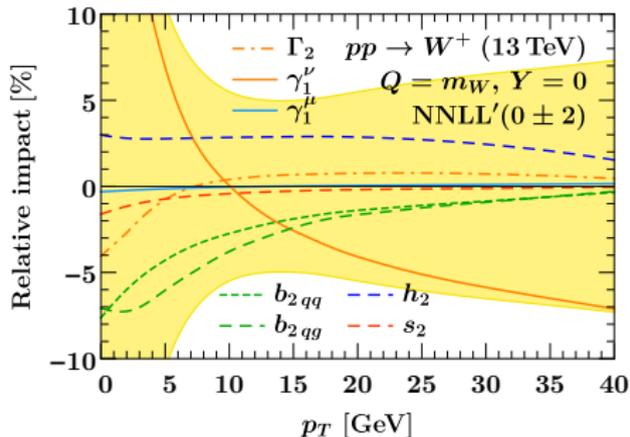
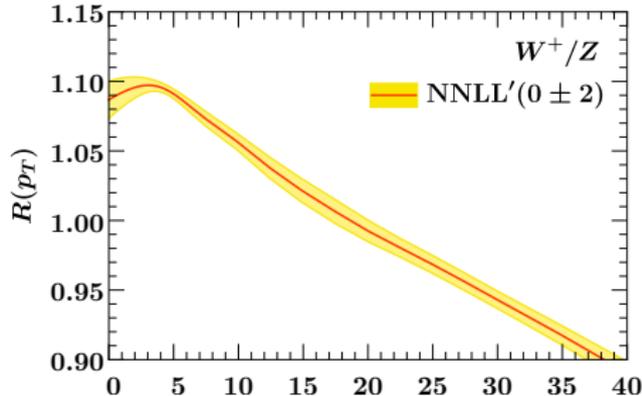
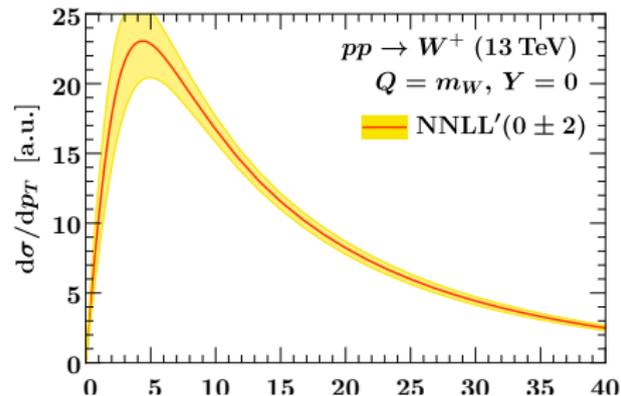
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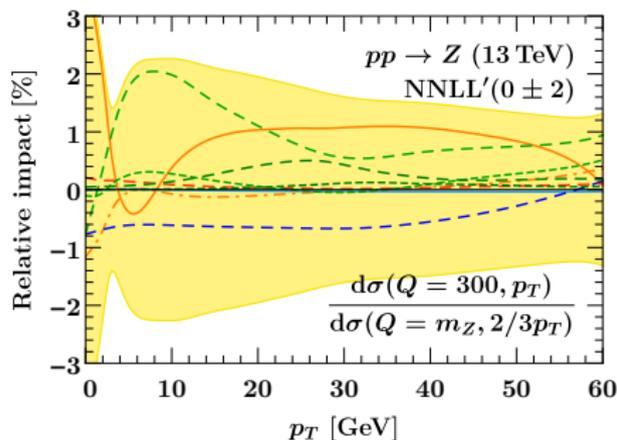
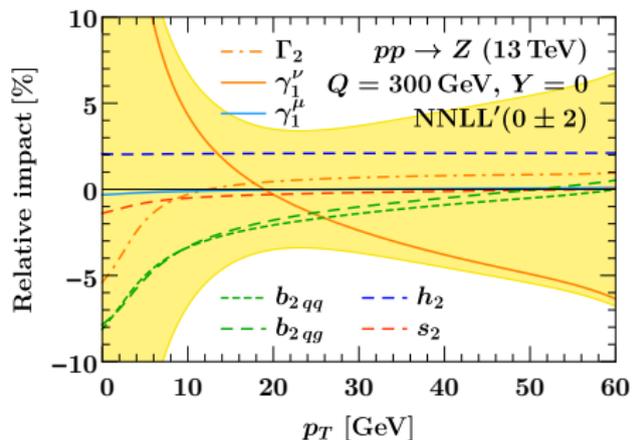
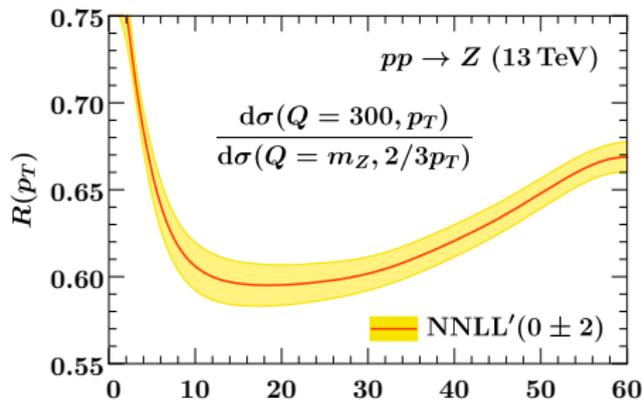
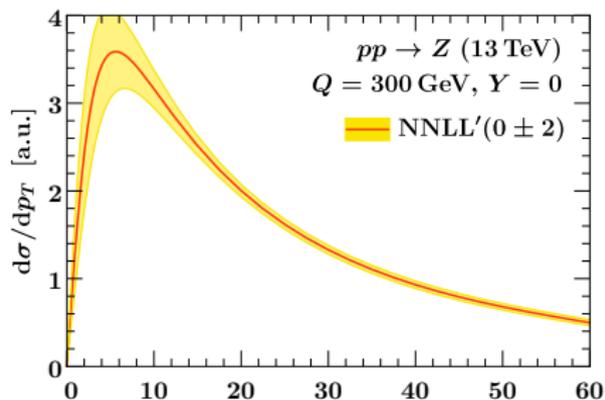
- h_2
- γ_1^μ
- b_2 : $q \rightarrow q, g \rightarrow q$
- Γ_2
- γ_1^ν
- s_2



W vs. Z.



Drell-Yan at High Q vs. Z Pole.



A theory prediction without an uncertainty is about as useful as a measurement without an uncertainty

- Uncertainties need to be reliable (small is not good enough ...)

Theory nuisance parameters overcome many problems of scale variations

- Allow to rigorously quantify pert. theory uncertainties and correlations
- Encode correct correlations
 - ▶ Between different p_T values, Q values, partonic channels, hard processes
 - ▶ Between different variables (\vec{p}_T , p_T^{jet} , \mathcal{T}_0 , τ , C , ...),
 - ▶ Multi-differential cases, cases with auxiliary measurements, ...
- Can be propagated straightforwardly
 - ▶ Including Monte Carlo, BDTs, neural networks, ...
 - ▶ Crucial for consistent treatment of theory uncertainties by experiments

⇒ A plethora of applications to explore ...